

Sustainable Computing for Fluid Dynamics via Physics-Informed Surrogates

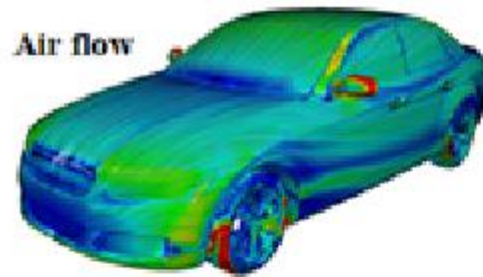
Gabriele Gianini

w/Luigi Ciceri, Corrado Mio, Jianyi Lin

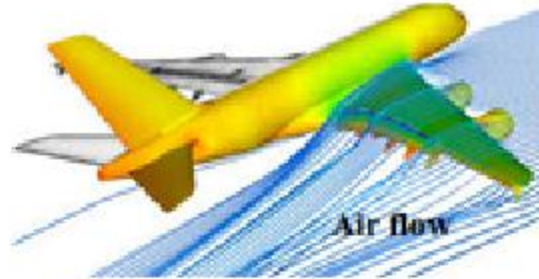
Green ICT & ICT for Green Workshop, 29 October 2025
ECSS 2025 - European Informatics Leaders Summit, Rennes

Computational Fluid Dynamics (CFD)

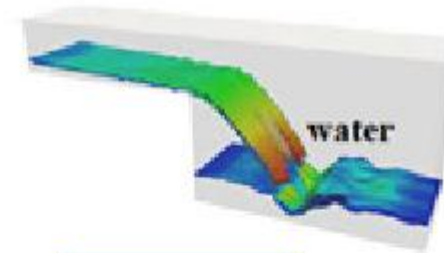
- CFD is the field of numerical simulation of flow-related problems
- It finds application in a number of diverse domains



Automobile



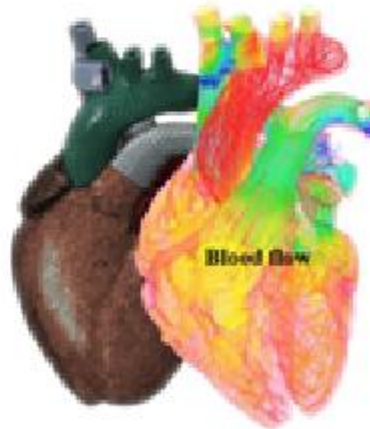
Aerospace



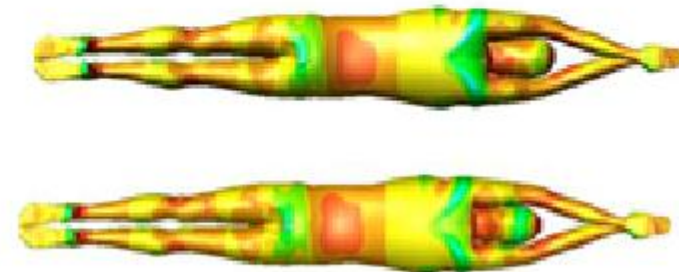
Water fall



Ventillation



Biomedical



Swinning

Review



Cite this article: Slotnick JP, Khodadoust A, Alonso JJ, Darmofal DL, Gropp WD, Lurie EA, Mavriplis DJ, Venkatakrishnan V. 2014 Enabling the environmentally clean air transportation of the future: a vision of computational fluid dynamics in 2030. *Phil. Trans. R. Soc. A* **372**: 20130317.
<http://dx.doi.org/10.1098/rsta.2013.0317>

One contribution of 13 to a Theme Issue 'Aerodynamics, computers and the environment'.

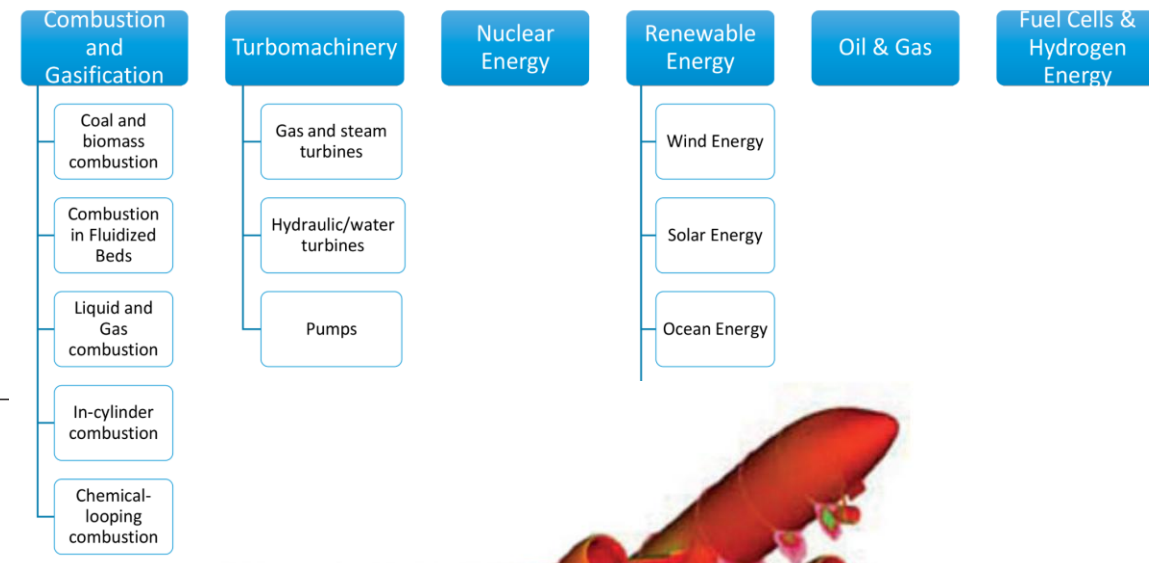
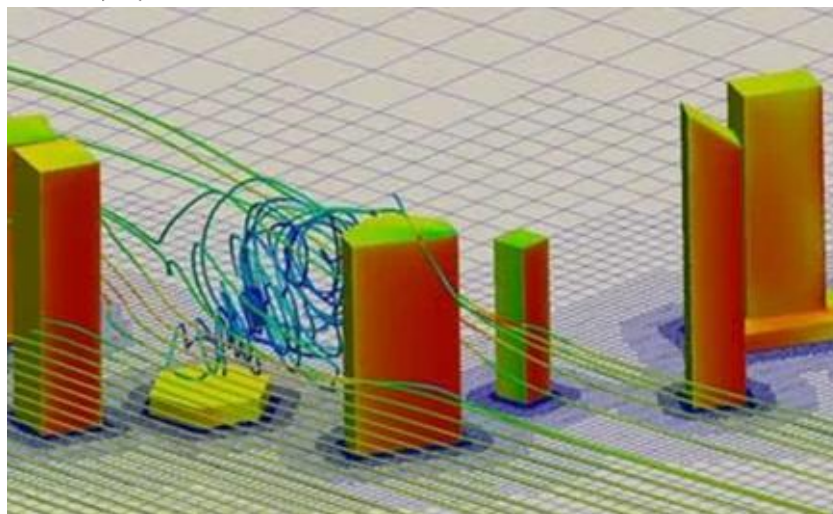
Subject Areas:
environmental engineering

Enabling the environmentally clean air transportation of the future: a vision of computational fluid dynamics in 2030

Jeffrey P. Slotnick¹, Abdollah Khodadoust¹, Juan J. Alonso², David L. Darmofal³, William D. Gropp⁴, Elizabeth A. Lurie⁵, Dimitri J. Mavriplis⁶ and Venkat Venkatakrishnan⁷

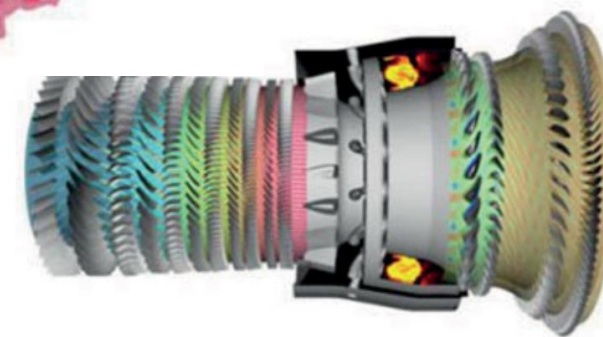
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Large Eddy Simulation

Turbo engine
Digital Twins



Key role in the design of efficient transportation, as well as urban landscapes design

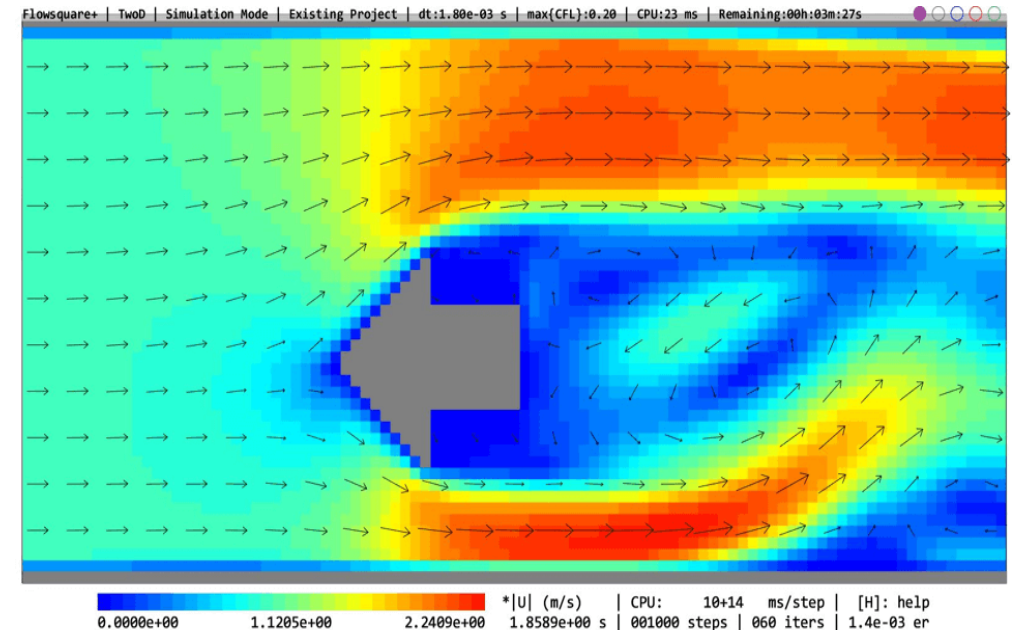
The task

Numerically **predicting behavior of fluids**

- Motion, forces, transport of heat/mass/momentum

By solving the governing physical equations, e.g. **Navier-Stokes'** under given

- Geometry/domain
- Physical params: ρ (density), μ (viscosity)...
- Boundary conditions (BCs)
- Initial conditions (ICs for transient problems)
 - Inlet fields (velocity/mass-flow, temperature)
 - Outlet fields (pressure/zero-gradient)
 - Walls (no-slip/slip, heat flux/temperature...)
- Forcing (volumetric sources):
 - gravity/buoyancy, porous drag



Numerics (implicit but important): discretization (FVM/FEM), mesh/resolution, time stepping, solver tolerances

Navier-Stokes Partial Differential Equations

- Often the target quantities are
 - Velocity vector field $\mathbf{v}(x,y,z)$, Pressure field $p(x,y,z)$,
- And the equations are the Navier-Stokes PDEs, e.g. for $\mathbf{v}$ and p

The diagram illustrates the Navier-Stokes equation for velocity $\mathbf{v}$, with terms grouped by physical meaning:

- MASS:** ρ (Density of the Fluid)
- ACCELERATION:** $\left(\frac{\partial \vec{\mathbf{v}}}{\partial t} + (\vec{\mathbf{v}} \cdot \nabla) \vec{\mathbf{v}} \right)$ (Change in Velocity over Time + Speed and Direction of Fluid)
- FORCE:** $\rho \vec{\mathbf{g}} - \nabla p + \mu \cdot \nabla^2 \vec{\mathbf{v}}$ (External Forces such as Gravity - Pressure Gradient + Internal Stress Forces (viscous effects))

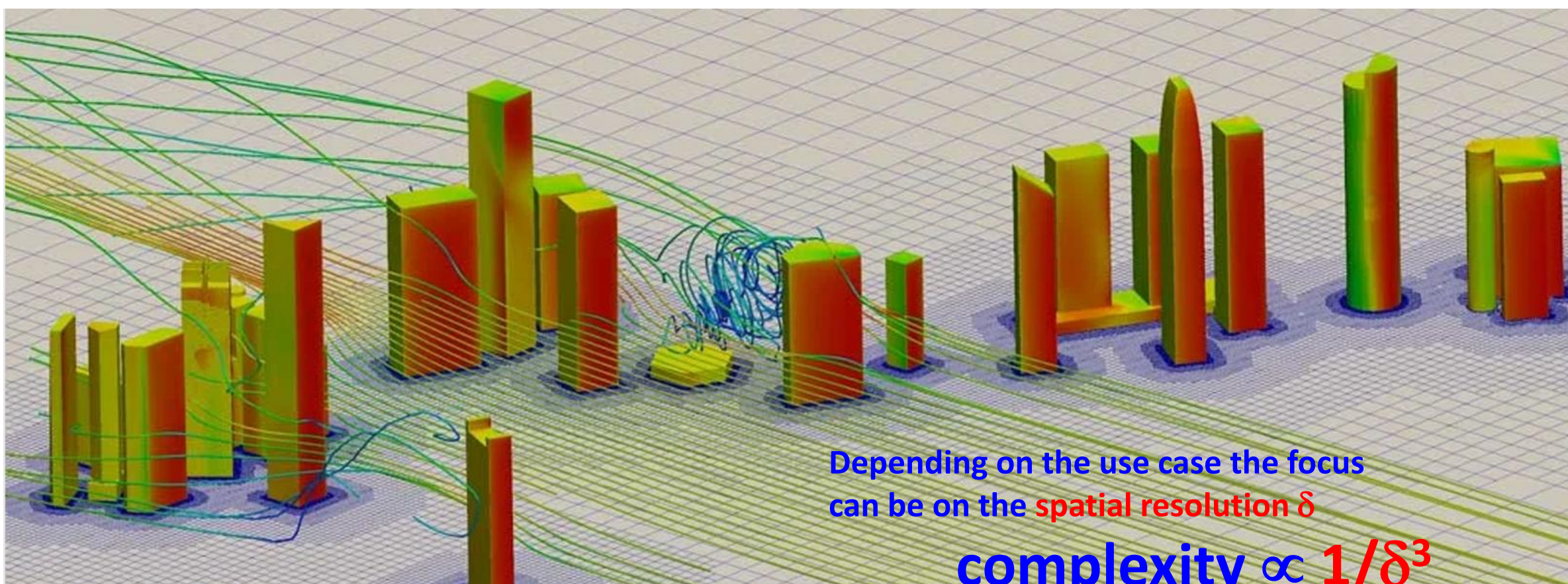
The equation is shown as:

$$\rho \cdot \left(\frac{\partial \vec{\mathbf{v}}}{\partial t} + (\vec{\mathbf{v}} \cdot \nabla) \vec{\mathbf{v}} \right) = \rho \vec{\mathbf{g}} - \nabla p + \mu \cdot \nabla^2 \vec{\mathbf{v}}$$

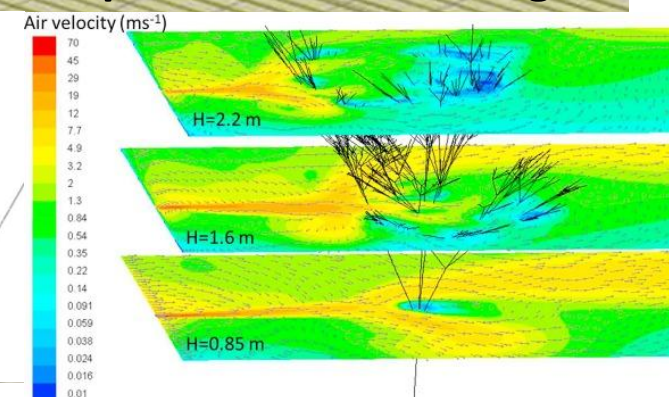
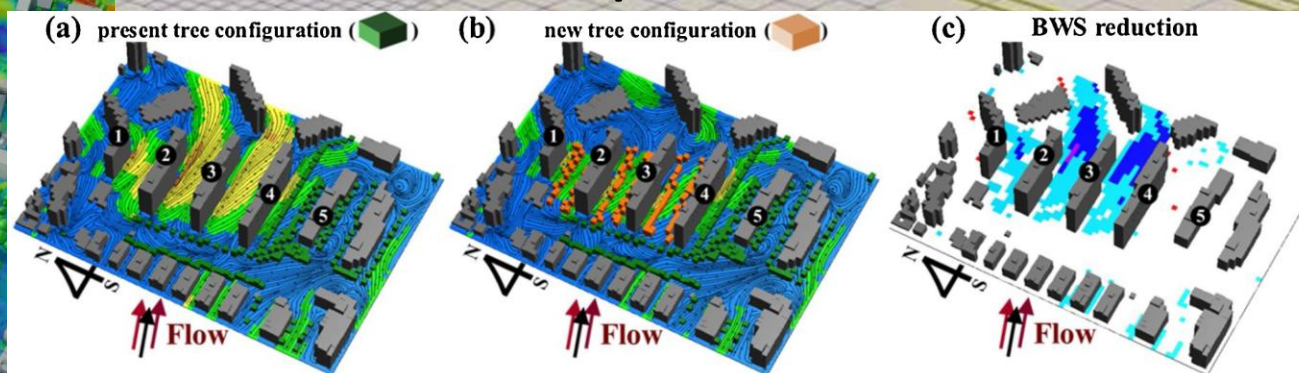
A blue arrow points from the equation to a blue starburst labeled "Space discretization", which leads to a list of numerical methods: FDE, FVM, and FEM.

Steady incompressible,
no forcing case

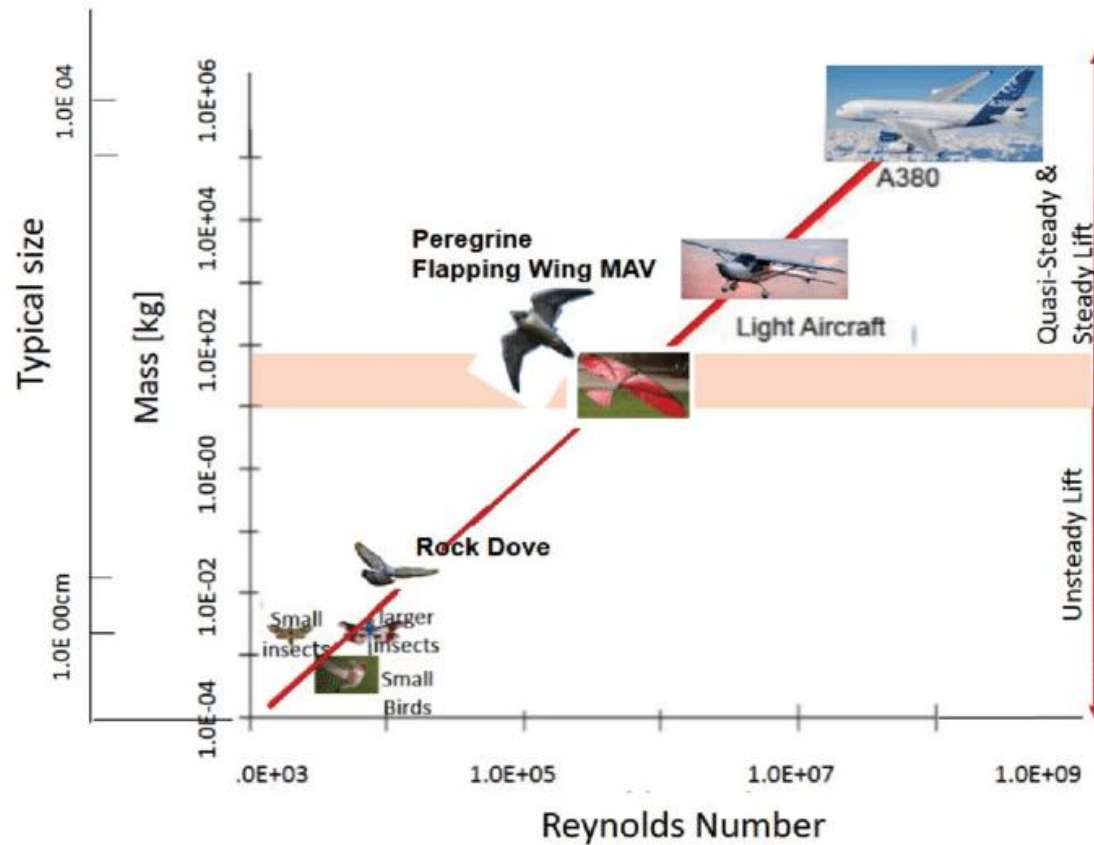
$$\rho(\mathbf{v} \cdot \nabla) \mathbf{v} = -\nabla p + \mu \nabla^2 \mathbf{v}$$



Critical for CFD of porous structures such as tree canopies in urban settings



Laminar vs. Turbulent flows

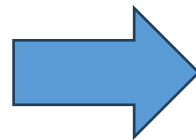


Flow pattern	Reynolds number	Description
	$Re < 5$	No separation, laminar steady flow
	$5 < Re < 45$	Pair of vortices, laminar steady flow
	$45 < Re < 150$	Laminar vortex street, unsteady flow
	$150 < Re < 3 \cdot 10^5$	Transitional unsteady flow
	$3 \cdot 10^5 < Re < 3 \cdot 10^6$	Turbulent unsteady flow
	$Re > 3 \cdot 10^6$	Turbulent vortex street, unsteady flow

<https://www.idealsimulations.com/resources/reynolds-number/>

These PDEs can become hard to solve in particular parameter ranges, especially with high $\rightarrow$ more turbulent systems, roughly **Reynolds number**

$$Re = \frac{\text{Inertial Force}}{\text{Viscous Force}} = \frac{\rho V L}{\mu}$$

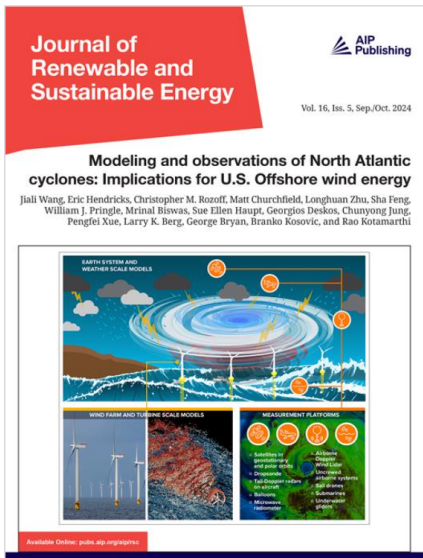


comput. complexity $\propto Re^{3-4}$

Re from 1 to 10^9

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RESEARCH ARTICLE | OCTOBER 23 2024

<https://doi.org/10.1063/5.0217320>

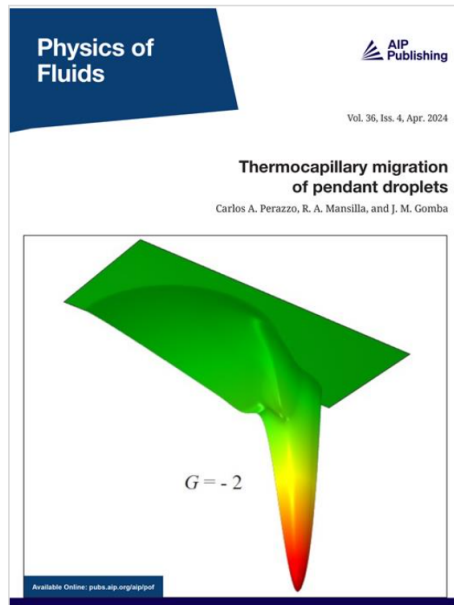
Computational fluid dynamics: Its carbon footprint and role in carbon reduction 🛒

Special Collection: [Flow, Turbulence, and Wind Energy](#)

[Xiang Yang](#)  ; [Wen Zhang](#) ; [Mahdi Abkar](#) ; [William Anderson](#) 

Volume 36, Issue 4

April 2024



RESEARCH ARTICLE | APRIL 02 2024

<https://doi.org/10.1063/5.0199350>

Estimating the carbon footprint of computational fluid dynamics 🛒

[J. A. K. Horwitz](#)  



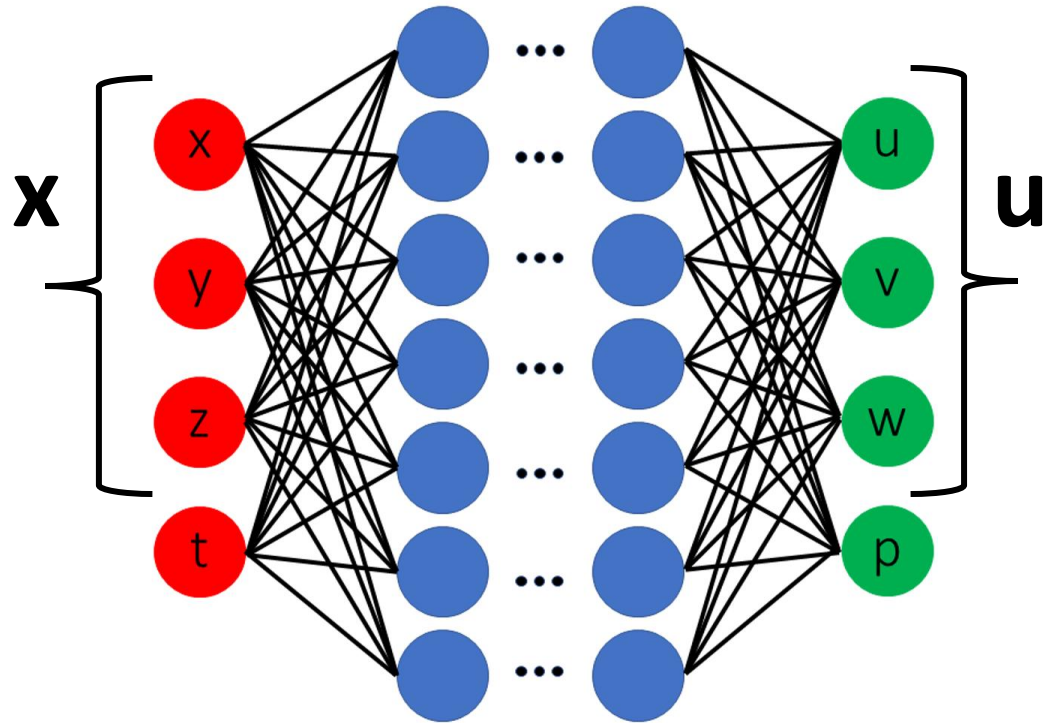
+ [Author & Article Information](#)

Physics of Fluids 36, 045109 (2024)

Order-of-magnitude estimated examples:
footprint **10^4 kg of CO₂** for single run

- dependent on year, hw efficiency, PUE grid

Deep Learning approach: ANN as CFD surrogates



A typical Green Computing approach

Teacher-Student pattern

Training ANN with data from CFD runs

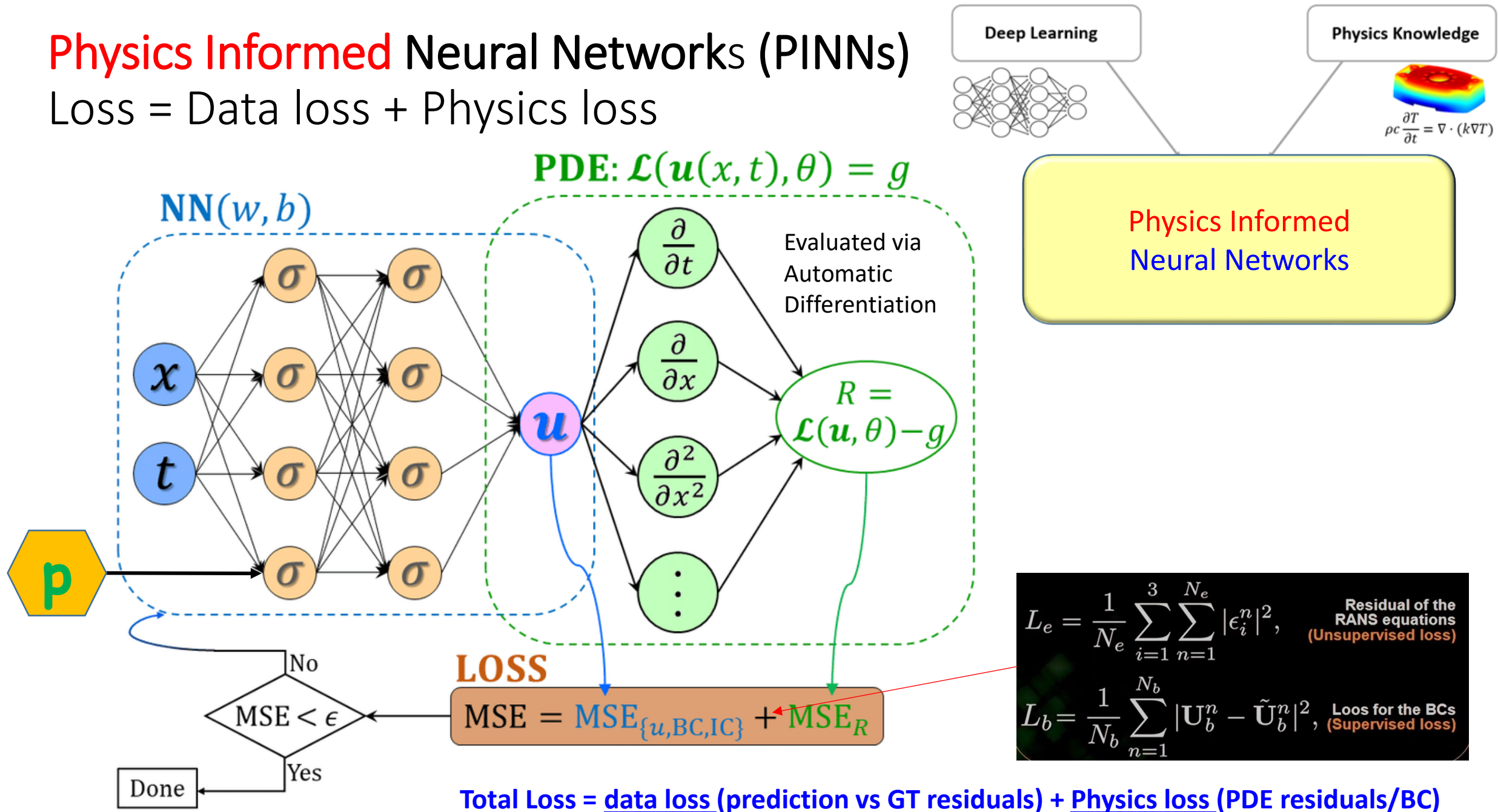
UP SIDE: can learn complex patterns

DOWN SIDE:

- Without physics in the loss/architecture
 - ANNs waste data learning the laws,
 - lack conservation awareness
 - and collapse outside their training bubble
- Data hungry!

Physics Informed Neural Networks (PINNs)

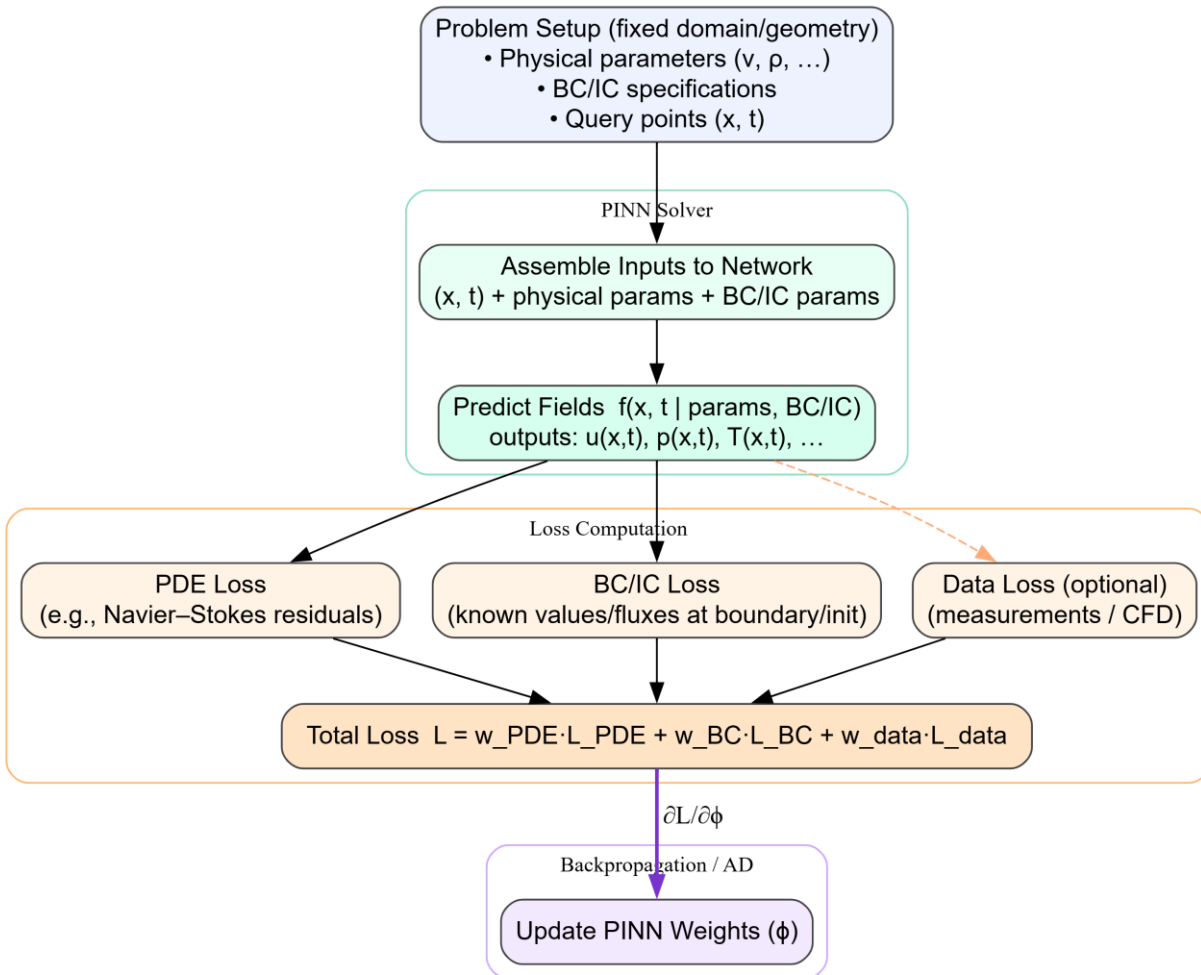
Loss = Data loss + Physics loss



PINNs learn $u_{\theta}(x, t | p)$

Predict $u()$ conditional to/generalizing over

- Initial Conditions/Boundary Conditions
- Physical parameters θ : ν, ρ, K, β_F
- Adding $\mathbf{p} = \{\text{BC/IC}/\theta\}$ as inputs to ANN and sampling on hypercube
 - interpolation **OK**,
 - extrapolation **fragile**



Domain Geometry is Hardcoded

- Possible geometrical awareness via inclusion of geometry parametrization in $\mathbf{p}$: **limited**
- **Must retrain for every new geometry!**

PI-PointNets add geometry awareness via point-clouds

Drop meshes and pass to point clouds. To obtain an embedding of the geometry



Journal of Computational Physics
Volume 468, 1 November 2022, 111510



Physics-informed PointNet: A deep learning solver for steady-state incompressible flows and thermal fields on multiple sets of irregular geometries

Ali Kashefi ^a ✉, Tapan Mukerji ^b ✉

We applied **PIPointNets** to **hybrid free flow and porous medium materials**

Problem Setup

- Geometry (point cloud + local features)
- Physical params ($v, \rho, K, \beta F, \dots$)
- BC/IC specs
- Query points (x, t)

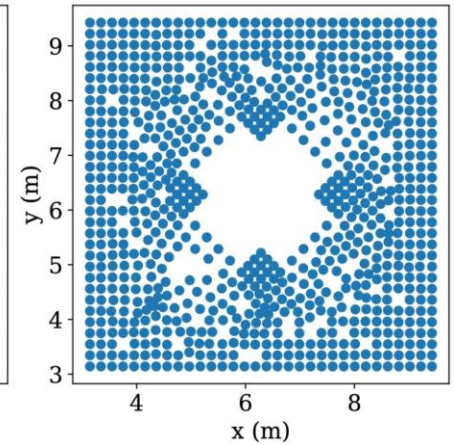
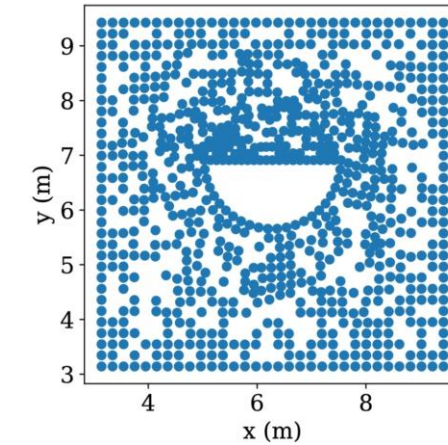
Shared Per-Point MLP $\rightarrow$ per-point features $\{h_i\}$

Global Shape Embedding z

Symmetric Pooling (max/mean/[max||mean])

(x, t) , params, BC

Assemble Solver Inputs
 $(x, t) + z + \text{physical/BC params}$



Predict Fields $f(x, t | z, \text{params}, \text{BC})$
outputs: $u(x, t), p(x, t), T(x, t), \dots$

PDE Loss
(NS residuals, Darcy–Forchheimer, ...)

BC/IC Loss
(known values/fluxes at boundary/init)

Data Loss (optional)
(measurements / CFD)

Total Loss $L = w_{\text{PDE}} \cdot L_{\text{PDE}} + w_{\text{BC}} \cdot L_{\text{BC}} + w_{\text{data}} \cdot L_{\text{data}}$

$\partial L / \partial \theta$

$\partial L / \partial \phi$

Backpropagation / AD

Update Encoder Weights (θ)
(per-point MLP + pooling)

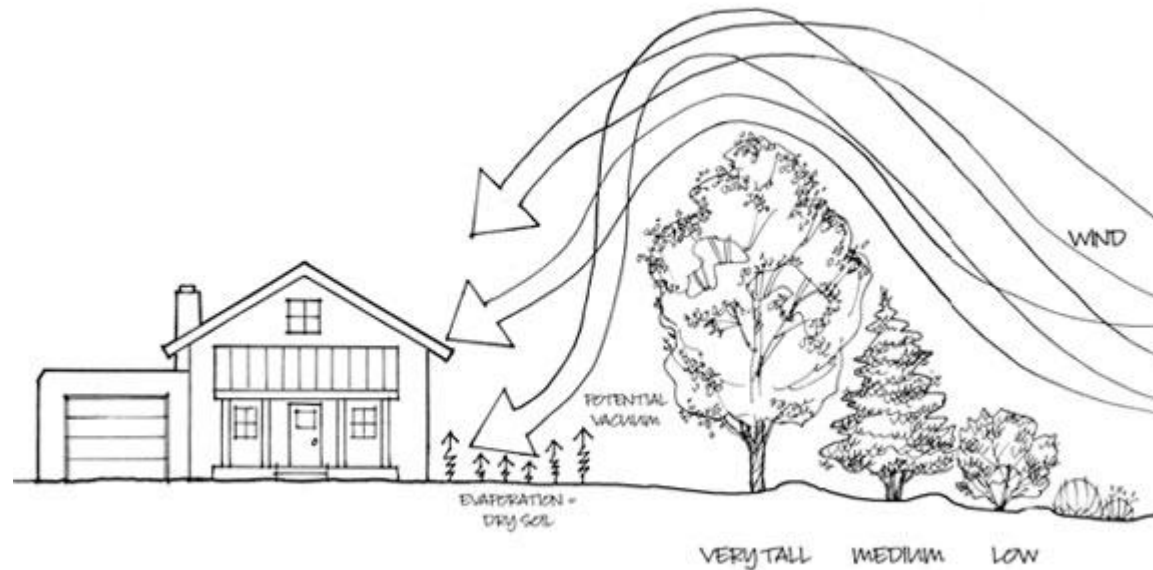
Update Solver Weights (ϕ)

Darcy-Forchheimer

$$\underbrace{\rho(\mathbf{v} \cdot \nabla) \mathbf{v}}_{\text{Navier-Stokes for incompressible fluid}} = -\nabla p + \underbrace{\mu \nabla^2 \mathbf{v}}_{\text{Darcy-Forchheimer}} - \left(\mu D + \frac{1}{2} \rho F |\mathbf{v}| \right) \mathbf{v}$$

Porous regions

- Flows that occur both **through and around** porous bodies at different scales are central to applications such as
 - submerged breakwaters,
 - rock-filled gabions,
 - industrial filters,
 - catalytic beds,
 - heat exchangers
 - coral reefs
 - plant canopies
 - **windbreaks** such as
 - vegetation barriers, fences, and perforated facades of buildings, used in various environmental and wind mitigation applications.

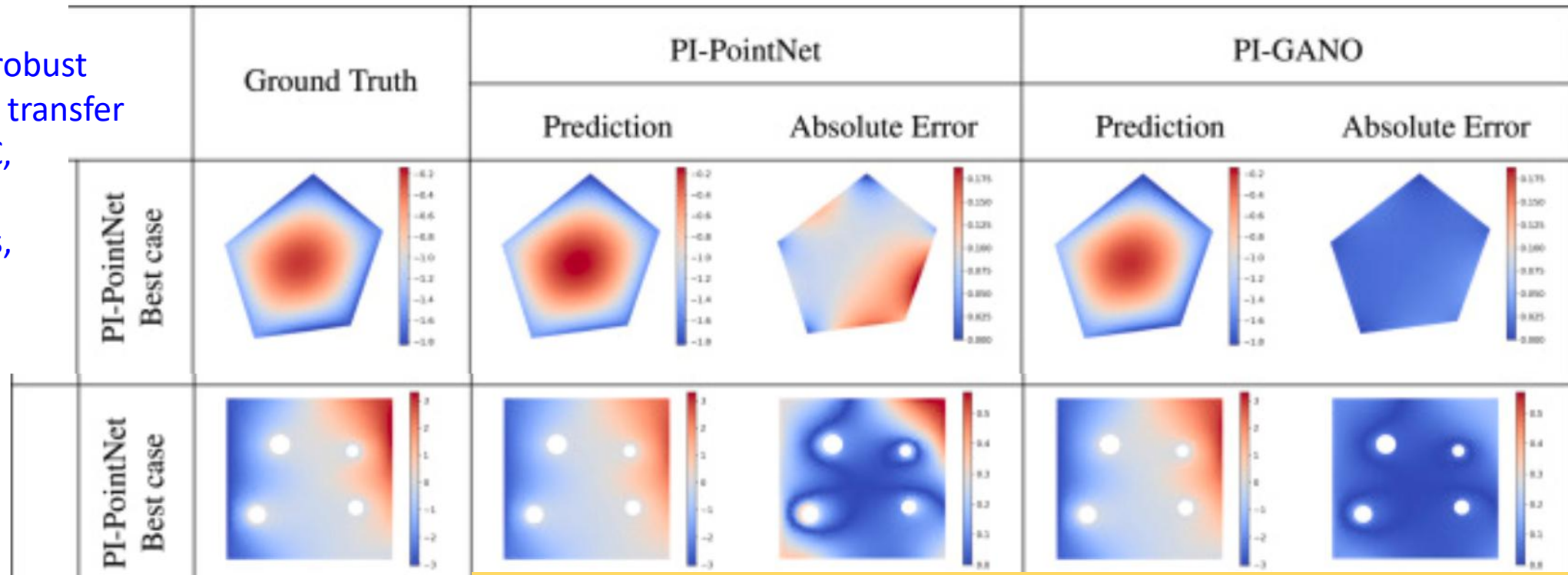


PI-GANOs map geometry via operators

From PIPN to PIGANO you move

- from a “geometry-conditioned solution function”
- to “a geometry-aware neural operator,”
 - learns a map between function spaces: input fields (coefficients/forcing/BC/geometry) to the solution field of a PDE, using layers that act on **functions** rather than finite-dimensional vectors

This enables robust zero/few-shot transfer across new BC, parameters, discretizations, geometry and forcing



We applied PIGANOs to hybrid freeflow and porous medium materials

Physics-Informed Geometry-Aware Neural Operator

Weiheng Zhong , Hadi Meidani 

Our architecture: from **PI-PointNet++** to **PI-GANO++**

If accuracy degrades at sharp interfaces/ geometry has fine, multi-scale details one can move **from PIPN to PIPN++**

- PIPN++ upgrades the encoder to a hierarchical, locality-aware version, adding multi-scale neighborhood features and local conditioning

We performed the same operation with **PIGANO** developing a **PIGANO++** architecture, which in analogy to PIPN++ brings

- hierarchical, locality-aware geometry into the neural-operator setting

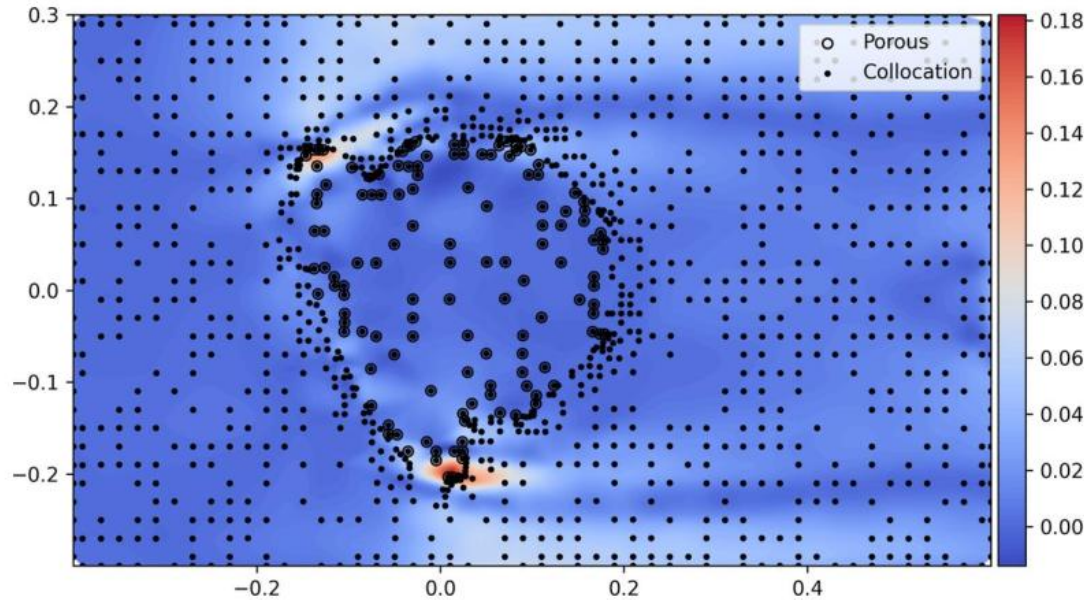
Yields better boundary/interface fidelity and generalization to fine geometric details—without giving up neural-operator flexibility across BCs, parameters, and meshes.

Our work:

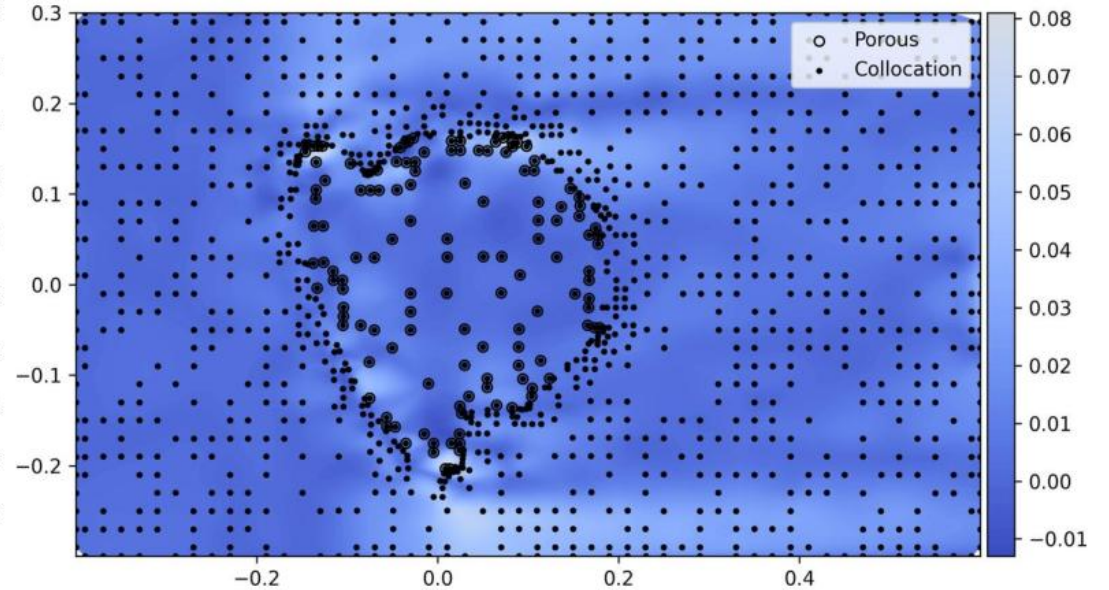
- developed **PIGANO++**

- applied **PIPN++** and **PIGANO++** to hybrid freeflow and porous medium materials

Example with 2D porous shape: PIPN++



(a) PIPN



(b) PIPN++ MRG

Error landscape

MAE in windbreak case studies



(a) Acacia



(b) Cypress



(c) Eucalyptus



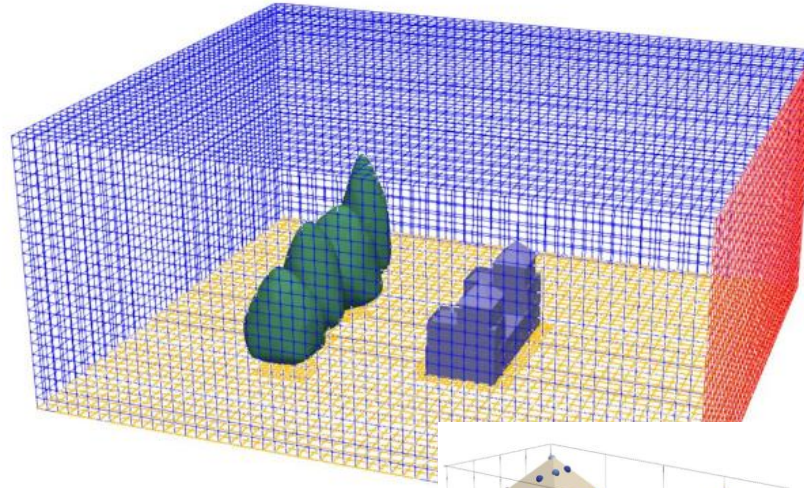
(d) Oak



(e) Pine

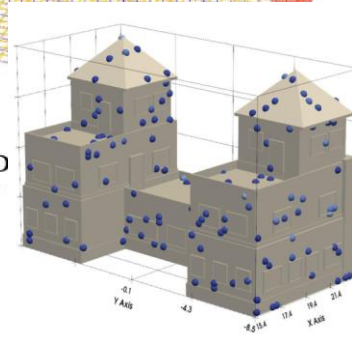


(f) Willow

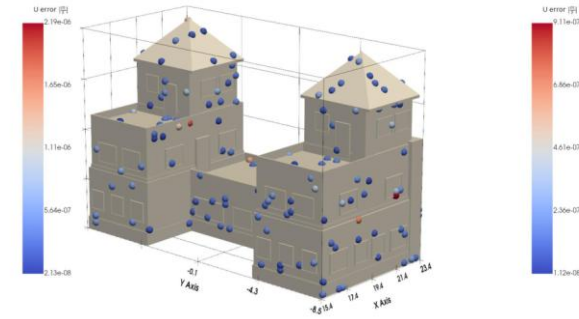


inlet, ground and outlet

(b) P



(a) PI-GANO



(b) PI-GANO++

	U_x		U_y		U_z		p	
Model	P.G.	P.G.++	P.G.	P.G.++	P.G.	P.G.++	P.G.	P.G.++
Total	$1.15 \cdot 10^{-7}$	$9.83 \cdot 10^{-8}$	$4.15 \cdot 10^{-8}$	$3.66 \cdot 10^{-8}$	$3.23 \cdot 10^{-8}$	$3.02 \cdot 10^{-8}$	$2.37 \cdot 10^{-12}$	$2.36 \cdot 10^{-12}$
Solid	$8.86 \cdot 10^{-8}$	$8.70 \cdot 10^{-8}$	$3.89 \cdot 10^{-8}$	$3.87 \cdot 10^{-8}$	$2.56 \cdot 10^{-8}$	$2.50 \cdot 10^{-8}$	$3.52 \cdot 10^{-12}$	$3.27 \cdot 10^{-12}$
Porous	$1.39 \cdot 10^{-7}$	$1.60 \cdot 10^{-8}$	$4.57 \cdot 10^{-8}$	$5.02 \cdot 10^{-8}$	$5.06 \cdot 10^{-8}$	$5.60 \cdot 10^{-8}$	$7.05 \cdot 10^{-12}$	$7.32 \cdot 10^{-12}$
Fluid	$1.14 \cdot 10^{-7}$	$9.51 \cdot 10^{-8}$	$4.13 \cdot 10^{-8}$	$3.59 \cdot 10^{-8}$	$3.13 \cdot 10^{-8}$	$2.88 \cdot 10^{-8}$	$2.12 \cdot 10^{-12}$	$2.09 \cdot 10^{-12}$
Max	$2.09 \cdot 10^{-6}$	$2.45 \cdot 10^{-6}$	$9.21 \cdot 10^{-7}$	$9.62 \cdot 10^{-7}$	$9.39 \cdot 10^{-7}$	$1.06 \cdot 10^{-6}$	$8.69 \cdot 10^{-11}$	$8.51 \cdot 10^{-11}$

Average **Times** $\text{CO}_{2e} = \text{PUE} \cdot P_{\text{IT}} \cdot \textcolor{red}{T} \cdot \text{CI}$

Method	Mesh / Collocation	Training Time (x factor CFD)	Inference Time (per case)
OpenFOAM (Laminar)	86 k cells	-	26 min 20.4 min
PIPointNets	2500 pts	110 min (4.23)	12 ms
PIGANO	3000 pts	301 min (14.75)	14 ms
PIGANO++	3000 pts	309 min (15.15)	17 ms

HW: HPC cluster, 32 CPU cores + NVIDIA A100

(2D) **ABC** for **PIPN**, (3D) **windbreaks** for **PI-GANO & PI-GANO++**

MEDES 2025 - THE 17TH INTERNATIONAL CONFERENCE ON
MANAGEMENT OF DIGITAL ECOSYSTEMS (HO CHI MIN CITY, VT)

Geometry-Aware Physics-Informed PointNets for Modeling Flows Across Porous Structures

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Questions?